

High Resolution Multibeam Systems for:

Hydrography

Offshore

Dredging

Defense

Research

SONIC 2026 Wideband Multibeam Echo Sounder

Features:

- Wideband 170 kHz 450 kHz
- Optional 90 kHz & 100 kHz
- Beam Widths to 0.45° x 0.45°
- $\cdot~$ Selectable swath 10° to 160°
- Pitch and Roll Stabilization
- Sounding Depth to 800m+
- Embedded processor/controller
- Low Weight, Volume and Power

System Description:

The Sonic 2026 is the most advanced broadband – wideband multibeam sonar of its kind.

With wide selectable operating frequencies between 170 k Hz and 450 kHz to 1 Hz resolution, and optional 90 kHz and 100 kHz, with sounding depth capability to 800m or more, the user has unparalleled flexibility to trade off resolution and range and controlling interference from other active acoustic systems.

In addition to selectable frequencies, the Sonic 2026 provides variable swath coverage selections from 10° to 160° the ability to rotate the swath to the port or to the starboard in real-time, as well as roll and pitch stabilization.

The Sonar consists of the three major components: a compact and lightweight projector, a receiver and a small dry-side Sonar Interface Module (SIM). Third party auxiliary sensors are connected to the SIM. The sonar data is tagged with GPS time.

The sonar operation is controlled from a graphical user interface on a PC or laptop typically equipped with navigation, data collection and storage applications software.

The operator sets the sonar parameters in the sonar control window, while depth, imagery and other sensor data are captured and displayed by the applications software.

Commands are transmitted through an Ethernet interface to the SIM. The SIM supplies power to the sonar heads, synchronizes multiple heads, time tags sensor data, and relays data to the applications workstation and commands to the sonar head.

The receiver head decodes the sonar commands, triggers the transmit pulse, receives, amplifies, beamforms, bottom detects, packages and transmits the data through the Sonar Interface Module via Ethernet to the control PC.

The elimination of separate processors and interface bottles makes this sonar well suited for AUV installation. Apart from the projector and receiver, the only hardware to be housed on the AUV is an interface board the size of a PC/104 board, Ethernet ports for interface, and the provision of isolated 48V DC power.

90/100 kHz	200 kHz	450 kHz
2° x 2°	1° x 1°	0.45° x 0.45°

Beam widths at selected frequencies (nadir)

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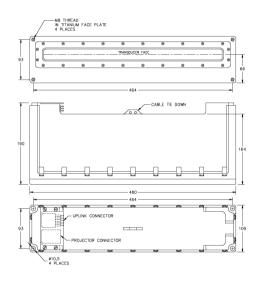
Systems Specification:

Frequency

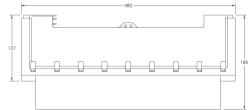
Beamwidth, Across Track Beamwidth, Along Track Number of Soundings

Selectable Swath Sector Sounding Depth Pulse Length Pulse Type Ping Rate Depth Rating Operating Temperature Storage Temperature 170 kHz - 450 kHz to 1 Hz resolution Optional 700 kHz 0.45° 0.45° Up to 1024 per swath, per head 10° to 160° 800 m+* 15 μ s - 2000 μ s Shaped CW Up to 60 Hz 100 m -10° C to 50° C -30° C to 55° C

Sonar Interface Module



Sonic 2026 Receiver



Sonic 2026 Projector

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Mains Power Consumption Uplink/Downlink:

Data Interface

Sync In, Sync out

Auxiliary Sensors

Deck Cable Length

Electrical Interface

90-260 VAC, 45-65 Hz 100 W (Sonar Head) 10/100/1000Base-T Ethernet 10/100/1000Base-T Ethernet TTL 1PPS, RS-232 RS-232 15 m

Mechanical

GPS

Receiver Dim (LWD) Receiver Mass Projector Dim (LWD) Projector Mass Sonar Interface Module Dim (LWH) Sonar Interface Module Mass 480 x 109 x 190 mm 12.9 kg 480 x 109 x 196 mm 13.4 kg 280 x 170 x 60 mm

2.4 kg

Sonar Options

TruePix[™] Imagery Output 90 kHz & 100 kHz Operation Switchable Forward Looking Sonar Output Raw Water Column Data Output I2NS[™] Integrated Inertial Nav. System Mounting Hardware & Assemblies 4000/6000m Immersion Depth Ratings Antifouling Coating Protection

*Max sounding depths depend on environmental conditions



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